

This section specifies the following electrical behavior of the 21285:

- PCI electrical conformance
- Absolute maximum ratings
- dc specifications
- ac timing specifications

9.1 PCI Electrical Specification Conformance

The 21285 PCI pins conform to the basic set of PCI electrical specifications in the *PCI Local Bus Specification, Revision 2.1*. See that document for a complete description of the PCI I/O protocol and pin ac specifications.

9.2 Absolute Maximum Ratings

The 21285 is specified to operate at a maximum frequency of 33 MHz at a junction temperature (T_j) not to exceed 125°C. Table 9-1 lists the absolute maximum ratings for the 21285. Stressing the device beyond the absolute maximum ratings may cause permanent damage. These are stress ratings only. Operating beyond the functional operating range is not recommended, and extended exposure beyond the functional operating range may affect reliability.

Table 9-1. Absolute Maximum Ratings

Parameter	Minimum	Maximum
Junction temperature, T_j	—	125°C
Supply Voltage, V_{dd}	—	3.9 V
Maximum voltage applied to signal pins	—	5.5 V
Maximum power P_{WC}	—	1.77 W @ 33 MHz
Storage temperature range, T_{stg}	-55°C	125°C

Table 9-2 lists the functional operating range.

Table 9-2. Functional Operating Range

Parameter	Minimum	Maximum
Voltage supply, V_{dd}	3.0 V	3.6 V
Operating ambient temperature, T_a	0°C	70°C

9.3 DC Specifications

Table 9-3 defines the dc parameters met by all 21285 PCI signals under normal operating conditions.

Note: In Table 9-3, currents into the chip (chip sinking) are denoted as positive (+) current. Currents from the chip (chip sourcing) are denoted as negative (–) current.

Table 9-3. DC Parameters

Symbol	Parameter	Condition	Minimum	Maximum	Unit
Power Signal					
V_{dd}	Supply voltage	—	3.0	3.6	V
PCI Signals					
V_{il}	Low-level input voltage ^a	—	–0.5	$0.3 V_{dd}$	V
V_{ih}	High-level input voltage ^a	—	$0.5 V_{dd}$	$V_{dd} + 0.5 V$	V
V_{ol}	Low-level output voltage ^b	$I_{out} = 1500 \mu A$	—	$0.1 V_{dd}$	V
V_{ol5V}	Low-level output voltage ^c	$I_{out} = 6 \text{ mA}$	—	0.55	V
V_{oh}	High-level output voltage ^b	$I_{out} = -500 \mu A$	$0.9 V_{dd}$	—	V
V_{oh5V}	High-level output voltage ^d	$I_{out} = -2 \text{ mA}$	2.4	—	V
I_{il}	Low-level input leakage current ^{a,e}	$0 < V_{in} < V_{dd}$	—	± 10	μA
C_{in}	Input pin capacitance	—	—	10.0	pF
C_{IDSEL}	idsel pin capacitance	—	—	8.0	pF
C_{clk}	pci_clk pin capacitance	—	5.0	12.0	pF
Non-PCI Signals					
V_{ihc}	IC input high voltage ^{d,e}	—	$0.8 \times V_{dd}$	$V_{dd} + 0.5$	V
V_{ilc}	IC input low voltage ^{d,e}	—	–0.5	$0.2 \times V_{dd}$	V
I_{ilc}^f	Input leakage current	$0 < V_{in} < V_{dd}$	–10	10	μA
V_{ohc}^g	High-level output voltage ^{d,e}	$I_{oh} = -4 \text{ mA}$	2.4	—	V
V_{olc}^g	Low-level output voltage ^{d,e}	$I_{ol} = 4 \text{ mA}$	—	0.4	V
V_{ohc}^h	High-level output voltage ^d	$I_{oh} = -12 \text{ mA}$	2.4	—	V
V_{olc}^h	Low-level output voltage	$I_{ol} = 12 \text{ mA}$	—	0.4	V
I_{ts}	Tristate leakage current	—	—	100	μA
C_{in}	Input pin capacitance	—	—	5	pF
C_{io}	Input/output pin capacitance	—	—	12	pF
I_{dd}	Power supply current	—	—	490	mA

a. Guarantees meeting the specification for the 5-V signaling environment.

b. For 3.3-V signaling environment.

c. For 5-V signaling environment.

d. Voltage measured with respect to V_{ss} .

e. IC-CMOS-level inputs (include IC and ICOCZ pin types).

f. Leakage currents for **ma[12:0]** and **ba[1:0]** are –200 μA minimum and 200 μA maximum.

g. Not including clocks.

h. Including clocks (**MCLK**, **flck**, and **sdclk[3:0]**).

9.4 AC Timing Specifications

The next sections describe the following specifications:

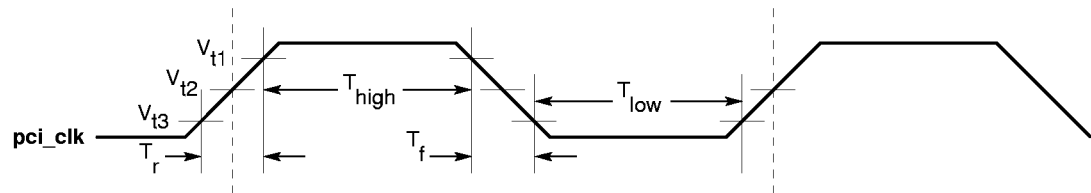
- PCI clock timing
- PCI signal timing
- PCI reset timing
- JTAG timing

9.4.1 PCI Clock Timing Specifications

The ac specifications consist of input requirements and output responses. The input requirements consist of setup and hold times, pulse widths, and high and low times. The output responses are delays from clock to signal. The ac specifications are defined separately for each clock domain (**pci_clk** and **fclk_in**) within the 21285.

Figure 9-1 shows the ac parameter measurements for the **pci_clk** signal, and Table 9-4 specifies **pci_clk** parameter values for clock signal ac timing. See also Figure 9-2 for a further illustration of signal timing.

Figure 9-1. PCI Clock Signal AC Parameter Measurement Conditions



Note:

V_{t1} – 2.0 V for 5-V clocks; 0.5 V_{cc} for 3.3-V clocks

V_{t2} – 1.5 V for 5-V clocks; 0.4 V_{cc} for 3.3-V clocks

V_{t3} – 0.8 V for 5-V clocks; 0.3 V_{cc} for 3.3-V clocks

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Table 9-4. PCI Clock Signal AC Parameters

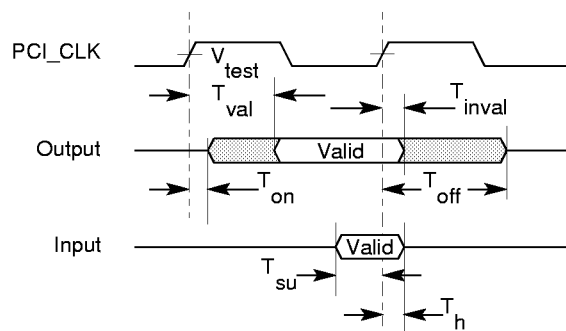
Symbol	Parameter	Minimum	Maximum	Unit
T_{cyc}	pci_clk cycle time	30	∞	ns
T_{high}	pci_clk high time	11	—	ns
T_{low}	pci_clk low time	11	—	ns
	pci_clk slew rate ^a	1	4	V/ns

a. 0.2 V_{cc} to 0.6 V_{cc}

9.4.2 PCI Signal Timing Specifications

Figure 9-2 and Table 9-5 show the PCI signal timing specifications. Table 9-6 correlates the ac parameters with the 21285 signal pins.

Figure 9-2. PCI Signal Timing Measurement Conditions



Note:
 V_{test} — 1.5 V for 5-V signals; 0.4 V_{cc} for 3.3-V signals

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Table 9-5. PCI Signal Timing Specifications

Symbol	Parameter	Minimum	Maximum	Unit
T_{val}	pci_clk to signal valid delay — bused signals ^{a,b,c}	2	11	ns
$T_{val(ptp)}$	pci_clk to signal valid delay — point-to-point ^{a,b,c}	2	12	ns
T_{on}	Float to active delay ^{a,b}	2	—	ns
T_{off}	Active to float delay ^{a,b}	—	28	ns
T_{su}	Input setup time to pci_clk—bused signals ^{a,b,c}	7	—	ns
$T_{su(ptp)}$	Input setup time to pci_clk—point-to-point ^{a,b,c}	10, 12	—	ns
T_h	Input signal hold time from pci_clk ^{a,b}	0	—	ns

- See Figure 9-2.
- All PCI interface signals are referenced to pci_clk.
- Point-to-point signals are req_l and gnt_l. Bused signals are ad, cbe_l, par, perr_l, serr_l, frame_l, irdy_l, trdy_l, devsel_l, stop, and idsel.

Table 9-6 lists the ac parameters that are applied in Table 9-5.

Table 9-6. PCI Signal Timing AC Parameters

Name	T_{val}	T_{val} (ptp)	T_{on}, T_{off}	T_{su}, T_h	T_{su} (ptp), T_h
ad[31:0]	y	—	y	y	—
cbe_l[3:0]	y	—	y	y	—
par	y	—	y	y	—
frame_l	y	—	y	y	—
irdy_l	y	—	y	y	—
trdy_l	y	—	y	y	—
stop	y	—	y	y	—
devsel_l	y	—	y	y	—
idsel	—	—	—	y	—
perr_l	y	—	y	y	—
serr_l	y	—	—	—	—
req_l	—	y	—	—	—
gnt_l	—	—	—	—	y
pci_irq_l	y	—	—	—	—

9.4.3 PCI Reset Timing Specifications

Table 9-7 shows the reset timing specifications for **pci_rst_l**.

Table 9-7. PCI Reset Timing Specifications

Symbol	Parameter	Minimum	Maximum	Unit
T_{rst}	pci_rst_l active time after power stable ^a	1	—	ms
$T_{rst-clk}$	pci_rst_l active time after pci_clk stable ^a	100	—	μ s
$T_{rst-off}$	pci_rst_l active-to-output float delay ^b	—	40	ns
	pci_rst_l slew rate ^a	50	—	mV/ns

- a. Applies to rising (deasserting) edge only.
 b. All PCI output drivers are asynchronously floated when **pci_rst_l** is asserted (except **ad**, **cbe_l**, and **par**, which are driven to 0 if **pci_cfn** is asserted).

9.4.4 JTAG Timing Specifications

Table 9-8 shows the JTAG timing specifications.

Table 9-8. JTAG Timing Specifications

Symbol	Parameter	Minimum	Maximum	Unit
T_{jf}	tck frequency	0	10	MHz
T_{jht}	tck high time	45	—	ns
T_{jlt}	tck low time	45	—	ns
T_{jrt}	tck rise time ^a	—	10	ns
T_{jft}	tck fall time ^b	—	10	ns
T_{js}	tdi, tms setup time to tck rising edge	10	—	ns
T_{jh}	tdi, tms hold time from tck rising edge	25	—	ns
T_{jd}	tdo valid delay from tck falling edge ^c	—	30	ns
T_{jfd}	tdo float delay from tck falling edge	—	30	ns

a. Measured between 0.8 V and 2.0 V.

b. Measured between 2.0 V and 0.8 V.

c. $C_1 = 50$ pF.

9.5 Memory and SA-110 Interface Timing

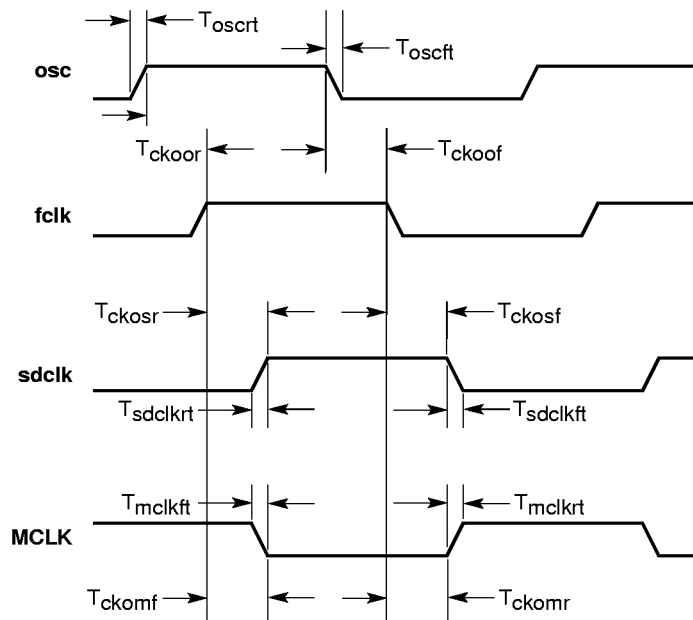
The timing parameters specified in this section are valid for the full range of voltage and temperature variations as stated in Sections 9.2 and 9.3. The ac specifications consist of input requirements and output responses. The input requirements consist of setup and hold times, pulse widths, and high and low times. The output responses are delays from clock to signal. All signal timings are referenced to the rising edge of **felk_in** unless otherwise stated.

All rise/fall AC parameters are measured from 10% to 90% of V_{dd} . All other AC parameters are measured from 50% V_{dd} of **felk_in** to 50% V_{dd} of signal specified.

9.5.1 SA-110, 21285, and SDRAM Clock Signal Timing Specifications

Figure 9-3 and Table 9-9 show the SA-110, 21285, and SDRAM clock signal timing specifications.

Figure 9-3. Clock Signal AC Parameter Measurement Conditions



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Table 9-9. SA-110, 21285, and SDRAM Clock Signal AC Parameters

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Name	Parameter	Minimum	Maximum	Unit
	osc period	15.0	$<T_{cyc}$	ns
	osc high time	6.7	—	ns
	osc low time	6.7	—	ns
T_{ckoor}	osc rising fclk rising	1.9	4.4	ns
T_{ckoof}	osc falling fclk falling	1.9	4.0	ns
T_{oscr}	osc rise time	0.5	2.0	ns
T_{oscf}	osc fall time	0.5	2.0	ns
T_{ckoi}	fclk to fclk_in delay ^a	—	—	ns
T_{ckomf}	fclk to MCLK delay - fclk rising	1.6	3.4	ns
T_{ckomr}	fclk to MCLK delay - fclk falling	1.8	3.9	ns
T_{mclkt}	MCLK rise time	0.5	2.0	ns
T_{mclktf}	MCLK fall time	0.5	2.0	ns
T_{ckosr}	fclk to sdclk delay - fclk rising ^b	1.6	3.6	ns
T_{ckosf}	fclk to sdclk delay - fclk falling ^b	1.6	3.2	ns

Table 9-9. SA-110, 21285, and SDRAM Clock Signal AC Parameters

(Sheet 2 of 2)

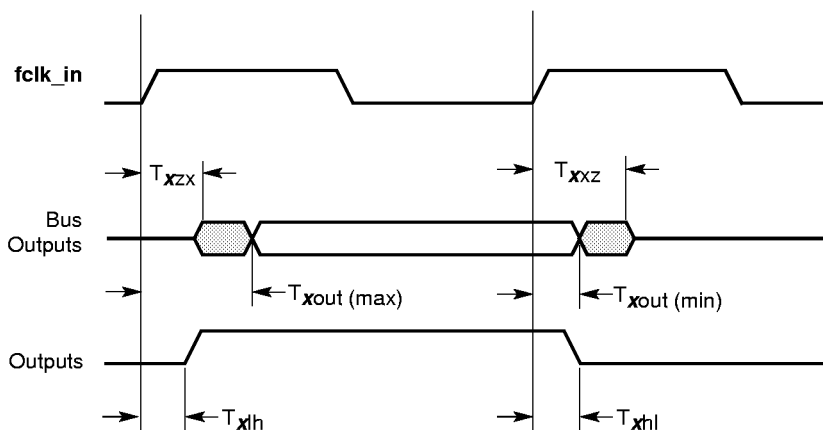
Name	Parameter	Minimum	Maximum	Unit
$T_{sdclkrt}$	sdclk rise time	0.5	1.0	ns
$T_{sdclkft}$	sdclk fall time	0.5	1.0	ns
T_{skew1}	Skew between rising edges on any two of sdclk[3:0]	—	0.5	ns
T_{skew2}	Skew between MCLK falling and any of sdclk[3:0] rising	—	0.5	ns

- a. This delay is not specified. It is imposed by etch delays in the module design. In the module design, the capacitive load and etch length on the following nets should be matched: 21285 **fcclk_in** output to 21285 **fcclk_in**; 21285 **MCLK** output to SA-110 **MCLK** pin; 21285 **sdclk[3:0]** outputs to SDRAM CLK pin.
- b. Any of **sdclk[3:0]**.

9.5.2 SA-110, 21285, and SDRAM Interface Timing Specifications

Figures 9-4 and 9-5 with Table 9-10 show the memory and SA-110 interface timing specifications.

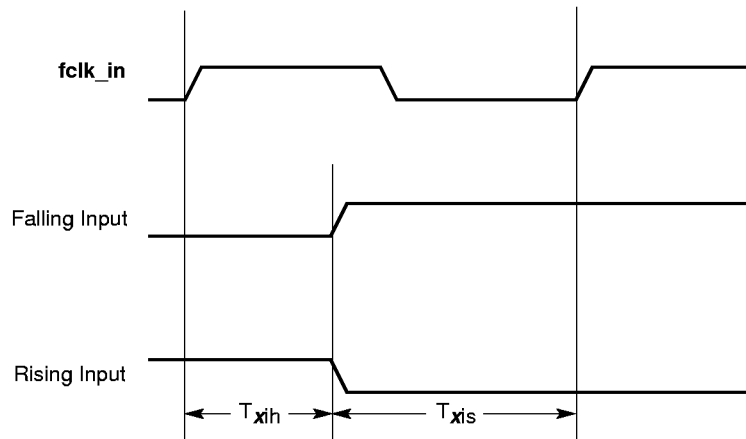
Figure 9-4. Interface Timing Measurement Conditions



Timing Symbol(s)	Corresponding Parameter Value
T_{xzx}	$T_{dzx}, T_{pzx}, T_{azx}, T_{dqmxz}, T_{maxz}, T_{cmdzx}, T_{cszx}$
T_{xxz}	$T_{dxz}, T_{pxz}, T_{axz}, T_{dqmxz}, T_{maxz}, T_{cmdxz}, T_{cszx}$
$T_{xout(max)}, T_{xout(min)}$	$T_{dout}, T_{pout}, T_{aout}, T_{dqmout}, T_{maout}, T_{cmdout}, T_{csout}$
T_{xlh}	$T_{xwlh}, T_{dwlh}, T_{rcslh}, T_{rdlh}, T_{wrh}, T_{xcslh}, T_{abelh}, T_{dbelh}$
T_{xhl}	$T_{xwhl}, T_{dwhl}, T_{rcshl}, T_{rdhl}, T_{wrhl}, T_{abeh}, T_{dbehl}$

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Figure 9-5. Input Timing Measurement Conditions



Timing Symbol(s)	Corresponding Parameter Value
T_{xih}	T_{dih} , T_{mrh} , T_{loh} , T_{rwh} , T_{clh} , T_{pih} , T_{dqmh} , T_{aih}
T_{xis}	T_{dis} , T_{mris} , T_{lois} , T_{rwis} , T_{clis} , T_{pis} , T_{dqms} , T_{ais}

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Table 9-10. Memory and SA-110 AC Parameters

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Name	Parameter	Minimum	Maximum	Unit
T_{dis}	T_{dis} data-in setup ^a	0.5	—	ns
T_{dih}	T_{dih} data-in hold ^a	1.6	—	ns
T_{pis}	T_{pis} parity-in setup	0.5	—	ns
T_{pih}	T_{pih} parity-in hold	1.6	—	ns
T_{dout}	Data-out delay	4.9	11.4	ns
T_{pouta}	Asynchronous parity-out delay (SA-110 write)	2.9	10.0	ns
T_{pouts}	Synchronous parity-out delay (21285 write)	4.9	11.8	ns
$T_{d zx}$	Data turn-on time	4.0	11.2	ns
$T_{d xz}$	Data turn-off time	4.0	11.2	ns
$T_{p zx}$	Parity turn-on time	4.0	11.1	ns
$T_{p xz}$	Parity turn-off time	4.0	11.1	ns
T_{ais}	Address input setup	1.7	—	ns
T_{aih}	Address input hold	1.0	—	ns
T_{aout}	Address output delay (includes rom_oe_l , rom_we_l)	4.4	11.8	ns
$T_{a zx}$	Address turn-on time	4.3	13.0	ns
$T_{a xz}$	Address turn-off time	4.3	13.0	ns
T_{dqma}	dqm[3:0] maximum output delay during SA-110 write, timed from SA-110 address in	—	9.1	ns
T_{dqmh}	dqm[3:0] minimum output hold during SA-110 write, timed from rising fclk_in	4.6	—	ns

Table 9-10. Memory and SA-110 AC Parameters

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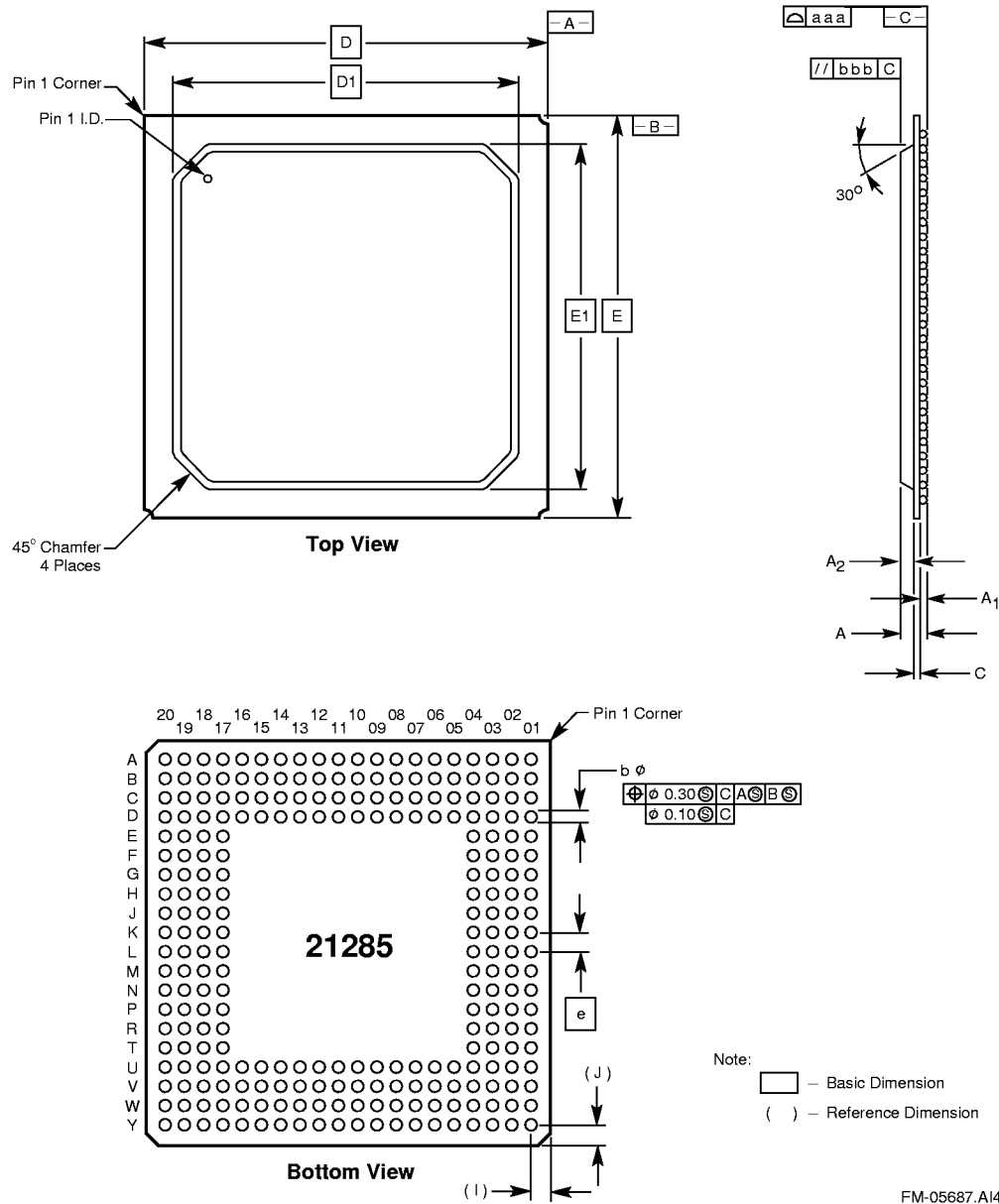
Name	Parameter	Minimum	Maximum	Unit
T _{dqms}	dqm[3:0] output delay during 21285 write	4.5	10.6	ns
T _{maout}	ma , ba output delay	4.7	10.8	ns
T _{cmdout}	cmd[2:0] output delay	5.0	11.5	ns
T _{csout}	cs_l[3:0] output delay	5.0	11.4	ns
T _{xwhl}	xd_wren_l assertion delay	5.3	11.1	ns
T _{xwlh}	xd_wren_l negation delay	5.1	11.7	ns
T _{dwhl}	d_wren_l assertion delay	4.5	9.3	ns
T _{dwlh}	d_wren_l negation delay	4.6	10.0	ns
T _{rcshl}	rom_ce_l assertion delay	4.5	9.6	ns
T _{rcslh}	rom_ce_l negation delay	4.6	10.2	ns
T _{rdhl}	xrd_l assertion delay	5.3	10.6	ns
T _{rdlh}	xrd_l negation delay	5.1	11.1	ns
T _{wrhl}	xwr_l assertion delay	5.4	10.8	ns
T _{wrlh}	xwr_l negation delay	5.1	11.2	ns
T _{xcshl}	xcs_l assertion delay ^b	5.0	11.1	ns
T _{xcslh}	xcs_l negation delay ^b	5.0	11.4	ns
T _{abehl}	ABE negation delay	5.1	10.3	ns
T _{abelh}	ABE assertion delay	4.8	10.4	ns
T _{dbehl}	DBE negation delay	4.4	9.1	ns
T _{dbelh}	DBE assertion delay	4.5	9.6	ns
T _{mr_{is}}	nMREQ input setup	1.6	—	ns
T _{mr_{ih}}	nMREQ input hold	0.9	—	ns
T _{lo_{is}}	LOCK input setup	0.9	—	ns
T _{lo_{ih}}	LOCK input hold	0.6	—	ns
T _{rw_{is}}	nRW input setup	0.5	—	ns
T _{rw_{ih}}	nRW input hold	1.1	—	ns
T _{cl_{is}}	CLF input setup	1.0	—	ns
T _{cl_{ih}}	CLF input hold	0.6	—	ns

a. For SA-110 writes to 21285, 21285 reads of SDRAM, and 21285 reads of ROM.

b. For **xcs** signals that are configured as outputs.

The 21285 is contained in an industry-standard 256 plastic ball grid array (PBGA) package, as shown in Figure 10-1.

Figure 10-1. 256 Plastic Ball Grid Array (PBGA) Package



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Table 10-1 lists the package dimensions in millimeters

Table 10-1. 256 Plastic Ball Grid Array (PBGA) Package Dimensions

Symbol	Dimension	Minimum Value	Nominal Value	Maximum Value
e	Ball pitch	—	1.27 BSC ^a	—
A	Overall package height	—	2.15	3.50
A ₁	Package standoff height	0.50	0.60	0.70
A ₂	Encapsulation thickness	—	—	2.50
b	Ball diameter	0.60	0.75	0.90
c	Substrate thickness	0.10	—	2.50
aaa	Coplanarity	—	—	0.20
bbb	Overall package planarity	—	—	0.25
D	Overall package width	26.80	27.00	27.20
D1	Overall encapsulation width	—	24.00	24.70
E	Overall package width	26.80	27.00	27.20
E1	Overall encapsulation width	—	24.00	24.70
I	Location of first row (x-direction)	—	1.44 reference ^b	—
J	Location of first row (y-direction)	—	1.44 reference ^b	—

- a. ANSI Y14.5M-1982 American National Standard Dimensioning and Tolerancing, Section 1.3.2, defines Basic Dimension (BSC) as: A numerical value used to describe the theoretically exact size, profile, orientation, or location of a feature or datum target. It is the basis from which permissible variations are established by tolerances on other dimensions, in notes, or in feature control frames.
- b. The value for this measurement is for reference only.